

Sliding Gate

Technical Specification

Sliding Gate;

Technical Specifications	SL600/24V
Power Supply (VAC 50Hz)	230
Motor Power Supply (Vac/Vdc)	24
Motor Power (W)	70
Current Draw (A)	1,8
Operating temperature (°C)	-20 ÷ +55
IP/Raiting (IP)	44
Maximum torque force (N)	600
Speed (cm/sec)	15/47
Weight (Kg)	15
Maximum Door Weight (Kg)	600

Sliding Gate Operator;

1. Programmable microprocessor should be used in the control unit inside the sliding gate motor.
2. The engine mechanics with the processor should be controlled with the help of the electric motor, the jam function should be protected by the current control circuit on the card, the motor and the card. The card should also be protected against overcurrents with glass fuse.
3. There should be jamming sensitivity in the closing direction and the motor should stop working at the moment of jamming and then continue its movement in the direction of opening.
4. There must be compaction sensitivity in the direction of opening and the engine must stop running at the moment of jamming.
5. It should work with transformer.
6. The motor body must be equipped to be able to intervene manually against power outages. In addition, it should continue working with the battery charge card as an option against power cuts.
7. Must have a card system suitable for operating 2 synchronized sliding gate motors.
8. It should have soft - start- soft - stop feature.
9. Speed control should be provided.
10. When the motor is running, flashing warning lamp should be used.
11. The red-green traffic light should support your connection.
12. After the motor is turned on, it should have automatic shut-off function and this function can be activated or deactivated optionally. Automatic closing time 5 sec. with 90 sec. between the control card should be adjusted as analog.
13. Sensors that will be used for security purposes in motor movements should be connected. These sensors should be able to be used for opening and closing. With the help of adjustable functions, if the object passes while the engine is shutting down, the door should move in the direction of opening, and after the object passes in this direction, the door should close automatically again. With the help of adjustable functions, if the object passes while the motor is opening, the door should stop, and when the object comes out, the motor should continue its movement in the direction of opening.
14. The internal or external remote control receiver must adapt to the system.
15. The Open and Close dry contacts on the barrier control card should be designed in accordance with the smart card system, card pass system (KGS) and automatic pass system (OGS).
16. Motor and Switch direction should be changed on electronic card at the same time.